

Backpropagation (反向傳播算法)

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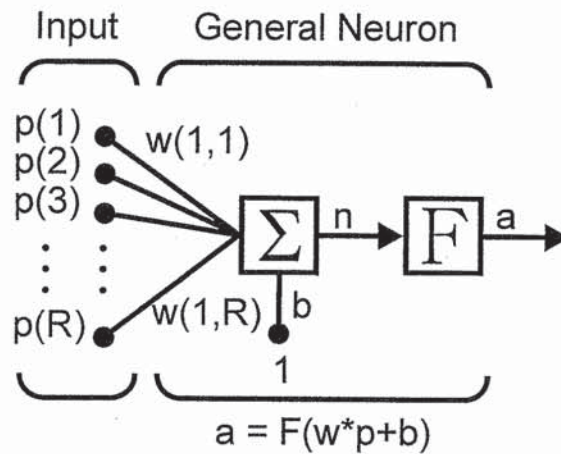
- *Momentum*
- *Adaptive learning rate*
- *Levenberg-Marquardt optimization*

Introduction

- Backpropagation was created by generalizing the Widrow-Hoff learning rule to multiple-layer networks and nonlinear differentiable transfer functions.
- Networks with biases, a sigmoid layer, and a linear output layer are capable of approximating any function with a finite number of discontinuities.
- Reference: Rumelhart DE, Hinton GE, Williams RJ, "Learning internal representation by error propagation", Rumelhart D and McClelland J, editors. *Parallel Data Processing*, Vol.1, Chapter 8, the M.I.T. Press, Cambridge, MA 1986 pp. 318-362.
- Feed-forward networks with up to three layers can be created and simulated with **initff** and **simuff**. Such networks can then be trained with the backpropagation training function **trainbp**, or with a faster version of backpropagation, **trainbpx**. Another function, **trainlm**, is even faster but requires large amount of memory.

Neuron Model

An elementary backpropagation neuron with R inputs is shown below.



- Neurons may use any *differentiable* transfer function F to generate their output.
 - Backpropagation networks often use the log-sigmoid transfer function **logsig**. The function generates outputs between 0 and 1 as the neuron's net input goes from negative to positive infinity.

$$\text{logsig}(n) = \frac{1}{1 + e^{-n}}$$

- Alternatively, backpropagation networks may use the tan-sigmoid transfer function **tansig**. The function generates outputs between -1 and 1 .

$$\text{tansig}(n) = \frac{2}{1 + e^{-2n}} - 1$$

- Occasionally, the linear transfer function **purelin** is used. The outputs can take any value.

The above transfer functions are differentiable and they are also *monotonic increasing* functions. That is, the output of each function increases as its input increases.

- In backpropagation it is important to be able to calculate the derivatives of any transfer function used. Each of the transfer functions above, **tansig**, **logsig**, and **purelin**, have a corresponding derivative function: **deltatan**, **deltalog** and

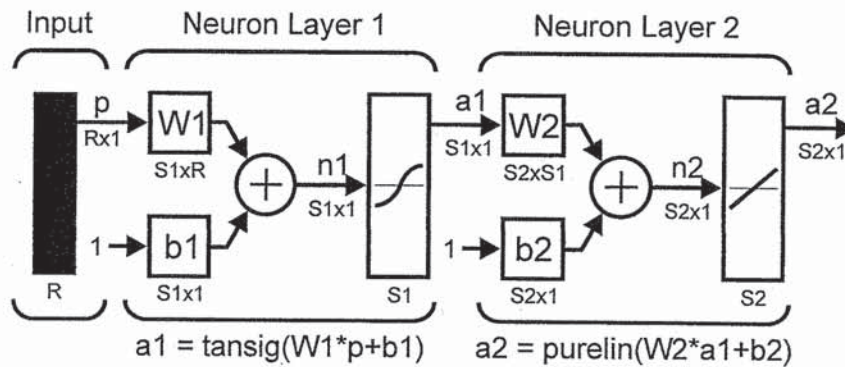
deltalin. To get the name of a transfer function's associated delta function, call the transfer function with the string '**delta**'.

```
tansig('delta')
```

```
ans = deltatan
```

Network Architecture (網絡架構)

Backpropagation networks often have *one or more* hidden layers of sigmoid neurons followed by an output layer of linear neurons.



- Multiple layers of neurons with nonlinear transfer functions allow the network to learn nonlinear and linear relationships between input and output vectors. The network shown above can be used as a general function approximator. It can approximate any function with a finite number of discontinuities, arbitrarily well, given sufficient neurons in the hidden layer.
- The output layer determines the range of output values. Linear output layer lets the network produce values outside the range -1 to $+1$. Sigmoid output layer (such as `logsig`) constrain the outputs (such as between 0 and 1).
- The function **simuff** simulates a feed-forward network. It takes the network input **p**, and the weights (權重) **W**, biases (偏移) **b**, and transfer function (轉換函數) for up to three layers, and returns each layer's output **a**.

$$[a1, a2] = \text{simuff}(p, W1, b1, \text{'tansig'}, W2, b2, \text{'purelin'});$$

- Below, **simuff** is called to calculate the outputs of one- and three-layer network.

$$a = \text{simuff}(p, W, b, \text{'tansig'})$$

$$[a1, a2, a3] = \text{simuff}(p, W1, b1, \text{'tansig'}, W2, b2, \text{'logsig'}, W3, b3, \text{'purelin'})$$

- If **simuff** is called with a single output argument, it will always return the output of the last layer.

$$a2 = \text{simuff}(p, W1, b1, \text{'tansig'}, W2, b2, \text{'purelin'})$$